Random Walks in Dependent Random Environments

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Outline

- Introduction
- General behavior
- Evaluating the drift for "swap model"
 - iid environment: trapping phenomenon
 - Markov environment
 - 2-dependent environment
 - Moving average environment
- Conclusions

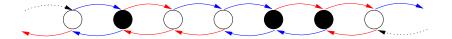
Introduction

(1-dimensional) Random Walk in Random Environment (RWRE):

- "Underlying" environment U is random but fixed (Assume U stationary and ergodic w.r.t. location)
- 2. Random walk $\{X_n, n = 0, 1, ...\}$ with conditional transition probabilities, determined by the environment:

$$\mathbb{P}(X_{n+1} = i+1 \mid X_n = i, \mathbf{U} = \mathbf{u}) = \alpha_i(\mathbf{u})$$

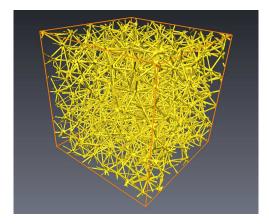
$$\mathbb{P}(X_{n+1} = i-1 \mid X_n = i, \mathbf{U} = \mathbf{u}) = \beta_i(\mathbf{u}) = 1 - \alpha_i(\mathbf{u}).$$



RWREs exhibit interesting and unusual behavior, not seen in ordinary random walks.

Introduction—Motivation

RWREs (*d*-dimensional) used in physics to model motion through disorganized (random) media.



Introduction—Goal

Theoretical behavior of *drift* in 1-dimensional RWRE well understood, but

- numerical evaluation?
- influence of dependent environments?
- d-dimensional case??

Our goal: develop theory and methods to compute the drift of the random walk for *dependent* environments.

Current results: for 1-dimensional case

General behavior

Drift behavior of $\{X_n\}$ follows, in principle, from Solomon 1975, Alili 1999

Key quantities:

$$\sigma_i = \sigma_i(\mathbf{u}) = \frac{\beta_i(\mathbf{u})}{\alpha_i(\mathbf{u})}$$
$$S = 1 + \sigma_1 + \sigma_1 \sigma_2 + \sigma_1 \sigma_2 \sigma_3 + \cdots$$

and

$$F = 1 + \frac{1}{\sigma_{-1}} + \frac{1}{\sigma_{-1}\sigma_{-2}} + \frac{1}{\sigma_{-1}\sigma_{-2}\sigma_{-3}} + \cdots$$

General behavior—Transience/Recurrence

Will $\{X_n\}$ ultimately move to $+\infty$ or $-\infty$, or not? Theorem 1 (Solomon-Alili)

1. If $\mathbb{E}[\ln \sigma_0] < 0$, then almost surely $\lim_{n \to \infty} X_n = \infty$.

2. If $\mathbb{E}[\ln \sigma_0] > 0$, then almost surely $\lim_{n \to \infty} X_n = -\infty$.

3. If $\mathbb{E}[\ln \sigma_0] = 0$, then almost surely $\liminf_{n \to \infty} X_n = -\infty$ and $\limsup_{n \to \infty} X_n = \infty$.

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General behavior—Law of Large Numbers

If $\{X_n\}$ ultimately moves to $+\infty$ or $-\infty$, how fast? Theorem 2 (Solomon-Alili)

1. If
$$\mathbb{E}[S] < \infty$$
, then almost surely $\lim_{n \to \infty} \frac{X_n}{n} = \frac{1}{2\mathbb{E}[S] - 1}$.
2. If $\mathbb{E}[F] < \infty$, then almost surely $\lim_{n \to \infty} \frac{X_n}{n} = \frac{-1}{2\mathbb{E}[F] - 1}$.
3. If $\mathbb{E}[S] = \infty$ and $\mathbb{E}[F] = \infty$, then almost surely $\lim_{n \to \infty} \frac{X_n}{n} = 0$.

 $\lim_{n\to\infty} X_n/n$ is the **drift** of the process $\{X_n\}$, denote by V.

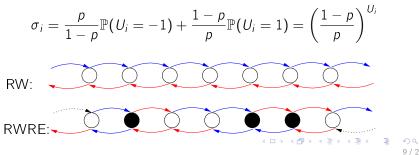
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Swap model

- Simple but versatile model with rich behavior
- $\alpha_i(\mathbf{u})$ and $\beta_i(\mathbf{u})$ only depend on \mathbf{u} via u_i
- ► Each U_i can only take value −1 (swap) or +1 (no swap).
- For some fixed value p in (0, 1), let $\beta_i(\mathbf{u}) = 1 \alpha_i(\mathbf{u})$ and

$$\alpha_i(\mathbf{u}) = \begin{cases} p & \text{if } u_i = 1\\ 1 - p & \text{if } u_i = -1 \end{cases}$$

As a result we have



Dependency structure

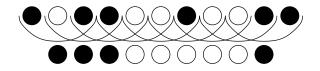
Standard iid case (Sinai 1983):

• Assumes the $\{U_i\}$ are iid with, for some $0 < \alpha < 1$,

$$\mathbb{P}(U_i = 1) = \alpha$$
, $\mathbb{P}(U_i = -1) = 1 - \alpha$.

Other possibilities for the environment states $\{U_i\}$:

- Markov environment
- k-dependent process
- Moving average of an iid environment:



lid case

Parameters α and p.

$$\mathbb{E}[\ln \sigma_0] = (1 - 2\alpha) \ln \left(\frac{1-p}{p}\right)$$

Hence $X_n \to +\infty$ a.s. if and only if either $\alpha > 1/2$ and p > 1/2, or $\alpha < 1/2$ and p < 1/2.

$$\mathbb{E}[S] = \sum_{n=0}^{\infty} \mathbb{E}\left[\sigma_1 \cdots \sigma_n\right] = \sum_{n=0}^{\infty} \left(\mathbb{E}\left[\left(\frac{1-p}{p}\right)^{U_1}\right]\right)^n = \frac{1}{1 - \mathbb{E}\left[\left(\frac{1-p}{p}\right)^{U_1}\right]}$$

iff
$$\mathbb{E}\left[\left(\frac{1-p}{p}\right)^{U_1}\right] = \frac{p}{1-p}(1-\alpha) + \frac{1-p}{p}\alpha < 1.$$

Hence when $\alpha > 1/2$ and $p \in (1/2, \alpha)$, or $\alpha < 1/2$ and $p \in (\alpha, 1/2)$, the drift is

$$V = \frac{1}{2\mathbb{E}[S] - 1} = (2p - 1)\frac{\alpha - p}{\alpha(1 - p) + (1 - \alpha)p} > 0$$

lid case

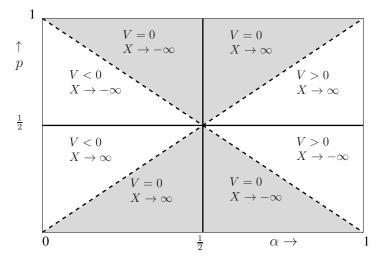


Figure 1: Drift regimes as a function of p and α . Grey areas: process transient, but drift is zero!

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lid case—Trapping phenomenon

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lid case—Trapping phenomenon

How can both $X_n \to \infty$ and V = 0 be true? (e.g. when $p > \alpha > 1/2$)

- Consider $\alpha = 3/4$, i.e. 25% of locations are black (swapped)
- When 1/2 , drift to the right is 'obvious'
- ▶ When 3/4 < p < 1,
 - ▶ still (strong) push to the right in majority of locations (hence $X_n \to \infty$)
 - ▶ but in remaining 25% of locations strong (!) push to the left

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- Consider $\alpha = 3/4$, i.e. 25% of locations are black (swapped)
- When 1/2 , drift to the right is 'obvious'
- ▶ When 3/4
 - still (strong) push to the right in majority of locations (hence X_n → ∞)
 - but in remaining 25% of locations strong (!) push to the left
- Hence V = 0 in latter case: difficult to cross barrier of many adjacent black locations !
- Apparently the "cut-off" value for p is equal to α ...
- in the iid case!

Markov environment

Let $\{\mathbf{U}_i\}$ be a stationary discrete-time Markov chain on $\{-1, 1\}$, with one-step transition matrix P given by

$$P = \left[\begin{array}{rrr} 1-a & a \\ b & 1-b \end{array} \right]$$

Parameters a, b and p

$$\mathbb{E}[\ln \sigma_0] = \frac{a-b}{a+b} \ln \frac{1-p}{p}.$$

so transience/recurrence behaviour is same as for iid case (with a/(a + b) playing the role of α). Again the drift is determined by:

$$\mathbb{E}[S] = \sum_{n=0}^{\infty} \mathbb{E}\left[\left(\frac{1-p}{p}\right)^{\sum_{i=1}^{n} U_i}\right].$$

Let, with $\sigma = (1-p)/p$,

$$G_u^{(n)}(\sigma) = \mathbb{E}\left[\sigma^{\sum_{i=1}^n U_i} \mid U_0 = u\right], \quad u \in \{\text{-1, 1}\}, \quad \text{in } \sigma \in \{\text{-1, 1, 1\}, \quad \text{in } \sigma \in \{\text{-1, 1,$$

Markov environment (cont'd)

Conditioning on U_0 we have,

$$G_{u}^{(n+1)}(\sigma) = \mathbb{E}\left[\sigma^{\sum_{i=1}^{n+1} U_{i}} \mid U_{0} = u\right] = \mathbb{E}\left[\sigma^{\sum_{i=2}^{n+1} U_{i}} \sigma^{U_{1}} \mid U_{0} = u\right]$$
$$= \sum_{v \in \{-1,1\}} P_{u,v} \sigma^{v} G_{v}^{(n)}(\sigma) .$$

In matrix notation, with column vector $\mathbf{G}^{(n)}(\sigma)$,

$$\mathbf{G}^{(n+1)}(\sigma) = PD\mathbf{G}^{(n)}(\sigma),$$

where $D = \operatorname{diag}(\sigma^{-1}, \sigma)$ so

$$PD = \left[egin{array}{ccc} (1-a)\sigma^{-1} & a\sigma \ b\sigma^{-1} & (1-b)\sigma \end{array}
ight]$$

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Also using
$$G_u^{(0)}(\sigma) = 1$$
, we find
 $\mathbf{G}^{(n)}(\sigma) = (PD)^n \mathbf{G}^{(0)}(\sigma) = (PD)^n \mathbf{1}$,

where $\mathbf{1} = (1, 1)^{\top}$, and hence

$$\mathbb{E}[S] = \sum_{n=0}^{\infty} \boldsymbol{\pi} \mathbf{G}^{(n)}(\sigma) = \boldsymbol{\pi} \sum_{n=0}^{\infty} (PD)^n \mathbf{1},$$

where $\boldsymbol{\pi}$ is stationary distribution vector of $\{U_i\}$. Hence,

$$V = \begin{cases} 1/\left[2\pi(I-PD)^{-1}\mathbf{1}-1\right] & \text{if } \operatorname{Sp}(PD) < 1\\ 0 & \text{else.} \end{cases}$$

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Markov environment (cont'd)

Working out details: • $\lim_{n \to \infty} X_n = \infty$ a.s. if either • a > b and $p \in \left(\frac{1}{2}, \frac{1-b}{(1-a)+(1-b)}\right)$, or • a < b and $p \in \left(\frac{1-b}{(1-a)+(1-b)}, \frac{1}{2}\right)$. • and

$$V = (2p-1)\frac{(1-b)(1-p) - (1-a)p}{\left(b + \frac{a-b}{a+b}\right)(1-p) + \left(a - \frac{a-b}{a+b}\right)p} > 0$$

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Comparison with iid case

To study impact of the (Markovian) dependence, reparameterize a and b via

$$\alpha = \mathbb{P}(U_0 = 1) = a/(a+b)$$

and

$$\varrho = \frac{\operatorname{Cov}(U_0, U_1)}{\operatorname{Var}(U_0)} = 1 - a - b,$$

yielding

$$V = (2p-1)\frac{\alpha - p + \varrho(1-\alpha - p)}{(\alpha(1-p) + (1-\alpha)p)(1+\varrho) - \varrho}$$

(Taking $\rho = 0$ gives iid case)

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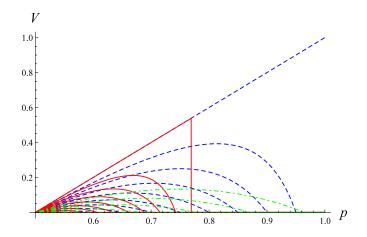


Figure 2: Drift for $\rho = 0$ (blue, dashed), $\rho = 0.3$ (red,solid), and $\rho = -0.3$ (green,dotdashed) as a function of ρ . From highest to lowest curves for $\alpha = 1, 0.95, \ldots, 0.55$ (for $\rho = 0$ and $\rho = 0.3$), and for $\alpha = 0.75, 0.70, \ldots, 0.55$ (for $\rho = -0.3$).

Other types of dependence model

Setup:

- Let {Y_i, i ∈ ℤ} be auxiliary Markov chain on {1,..., m} for some m (stationary and ergodic)
- ▶ Let $U_i = g(Y_i)$ for some given function $g: \{0, ..., m\} \rightarrow \{-1, 1\}$

Covers (a.o.):

- ▶ Markov environment (*U_i* and *Y_i* coincide)
- 2-dependent environment (4 × 4 transition matrix)
- ► Moving average environment (8 × 8 transition matrix)

Markov analysis easily extended, but now need to study larger matrix *PD*.

Using Perron–Frobenius theory and the implicit function theorem we identify where drift is 0

Moving average environment

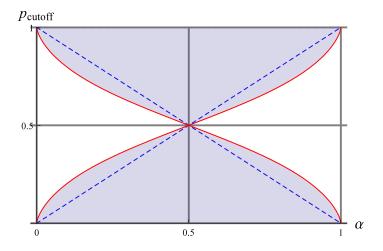


Figure 3: Cutoff values for the moving average process as function of α

Moving average environment

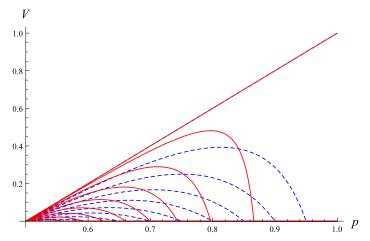


Figure 4: Red: Drift for the moving average environment as a function of p for $\alpha = 1, 0.95, \ldots, 0.55$ (from highest to lowest curves). Blue: comparison with the independent case.

Conclusions

- RWREs are interesting (trapping phenomenon)
- Construction of swap models with (a.o.) k-dependent and moving average environments, using auxilliary Markov chain
- Dependent environments affect the drift
- Cut-off values for p where drift becomes zero are determined via Perron–Frobenius theory

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Thanks for your attention!