

# Delays at signalised intersections with exhaustive traffic control

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## Model description

In this paper we provide an analysis for signalised traffic intersections with general renewal arrivals and vehicle-actuated, *exhaustive* traffic control. Nonconflicting traffic flows are divided into  $M$  groups that receive a green light simultaneously (e.g., flows 1, 2, 6, and 7 in Figure 1). The control policy is exhaustive, meaning that a green phase ends after the departure of the last vehicle in any flow that faces a green light.

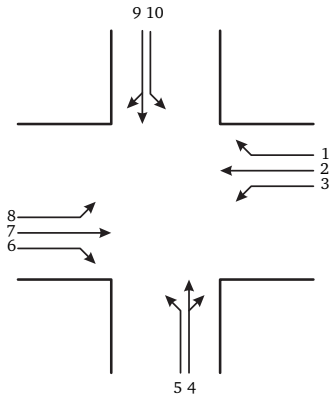


Figure 1: A traffic intersection consisting of 10 flows.

To model the intersection, we use a *polling system* with multiple queues being served simultaneously. First, we analyse this system under Heavy-Traffic (HT) conditions and Light-Traffic (LT) conditions. Subsequently, we develop a closed-form approximation for the mean delay of an arbitrary vehicle using an interpolation between the LT and HT limits.

## Stability

We order the flows within the groups according to their traffic intensities. Denote by  $\{g, 1\}$  the flow with the highest traffic intensity  $\rho_{g,1}$  in group  $g = 1, \dots, G$ , and so on. We refer to this flow as the *dominant* flow of group  $g$ . We show that only the dominant flows play a role in the stability condition:

$$\sum_{g=1}^M \rho_{g,1} < 1.$$

The total amount of traffic arriving per time unit is denoted by  $\rho = \sum_{g,j} \rho_{g,j}$ .

## Heavy traffic

We introduce the *relative traffic intensities*  $\hat{\rho}_{g,j} = \rho_{g,j}/\rho$ , and use them to define  $L = \sum_g \hat{\rho}_{g,1}$ , the total relative load of the dominant flows. The distribution of the scaled delay of a vehicle in flow  $\{g, j\}$  under HT conditions ( $L\rho \uparrow 1$ ) is

$$(1 - L\rho)W_{g,j} \xrightarrow{d} \begin{cases} 0 & \text{w.p. } \frac{\hat{\rho}_{g,1} - \hat{\rho}_{g,j}}{L - \hat{\rho}_{g,j}}, \\ U \times \Gamma_L & \text{w.p. } \frac{1 - \hat{\rho}_{g,1}/L}{1 - \hat{\rho}_{g,j}/L}, \end{cases}$$

where  $U$  is a uniformly distributed random variable and  $\Gamma_L$  has a Gamma distribution. This is shown using the Heavy Traffic Averaging Principle (from the polling literature) combined with HT fluid limits for the intersection (see Figure 2).

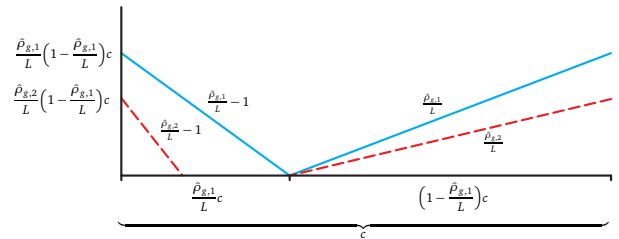


Figure 2: Heavy-traffic fluid limits for the scaled delays of two flows in group  $g$ .

## Approximation

We have developed a closed-form approximation

$$\mathbb{E}[W_{g,j}] \approx \frac{A + B\rho + C\rho^2}{1 - L\rho}, \quad (1)$$

where  $A$ ,  $B$ , and  $C$  are chosen such that that (1) is asymptotically correct in the LT and HT limits. Figure 3 shows an accurate approximation of the mean delay in a real-life example.

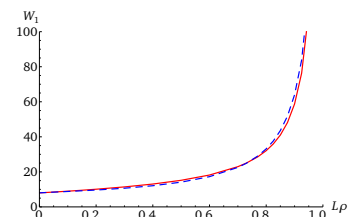


Figure 3: Approximated (blue) and simulated (red) mean delays.