

Problem: assign rescuers to victims

- each victim may need more than one rescuer
- we want to minimise the distance that rescuers need to cover to reach their assigned victims.

Solution

- Establish the distance of every rescuer to its closest victim
- Select the closest k rescuers for every victim
- Disregard the matched victims & rescuers
- Finish if no additional victims have been saved in the last iteration

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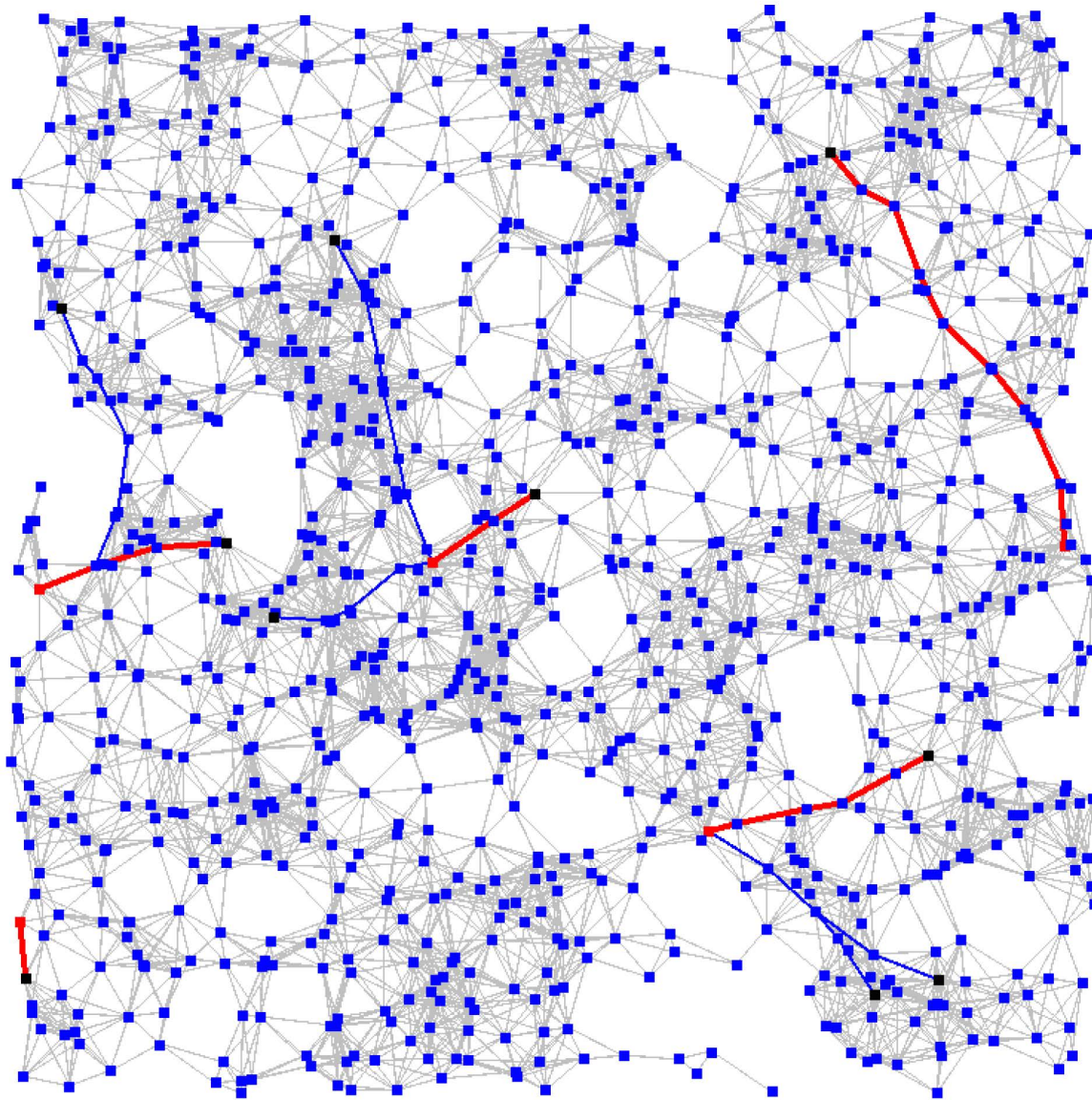
finish ← false;
until · agree · on finish do
  /* 1st Stage: */
  /* Establishing the distance to victims */
  D ←  $\mu Z$ .min1(source, ⟨dist⟩Z);

  /* 2nd Stage: */
  /* Computing the rescuers paths */
  rescuers ←  $\mu Z$ .init ∪ ⟨⟨grad⟩⟩Z;

  /* 3rd Stage: Engaging rescuers */
  finish ← false;
  /* engaging the rescuers */
  engaged ←  $\mu Z$ .choose ∪ ⟨cograd⟩Z;
  /* updating victims and available rescuers */
  victim' ← victim;
  victim ← victim ∧ ¬saved;
  rescuer ← rescuer ∧ engaged ≠ ∅;
  /* determining termination */
  finish ← (victim' == victim);

  /* 4th Stage: Checking success */
  if · agree · on ¬victim
    /* ended with success */
  else
    /* ended with failure */

```



Randomly generated graph:
1000 landmarks, 5 victims
and 10 rescuers.

Each victim can be reached
by more than one rescuer, the
closer one is selected.