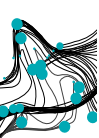


# Evaluating a process-aware IDS for smart grids on distributed hardware

Joint work with Kai Oliver Großhanten and Anne  
Remke

This research is conducted as part of the ISoLATE project (CS.016)  
funded by NWO.



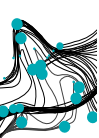
# Overview

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- ▶ Motivation
- ▶ Attack model
- ▶ Approach
- ▶ Truly distributed approach I
- ▶ Side Note I
- ▶ Side Note II
- ▶ Truly distributed approach II
- ▶ Properties for real-life test case
- ▶ Next steps





# Motivation

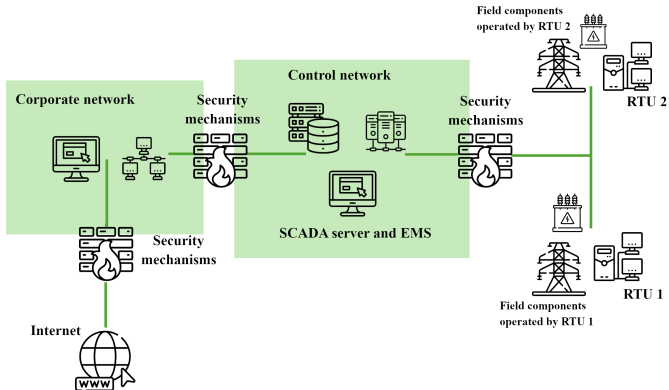
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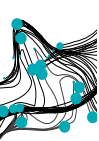
- ▶ smart and decentralised (**automated**) energy management comes with risks
- ▶ we need more accurate data to work with flexible renewables
- ▶ legacy SCADA software is under more & more attacks



# Motivation



*paradigm of security through obscurity and air gap*



# Motivation

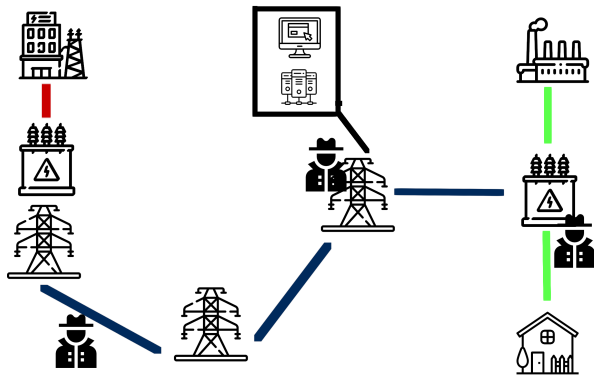
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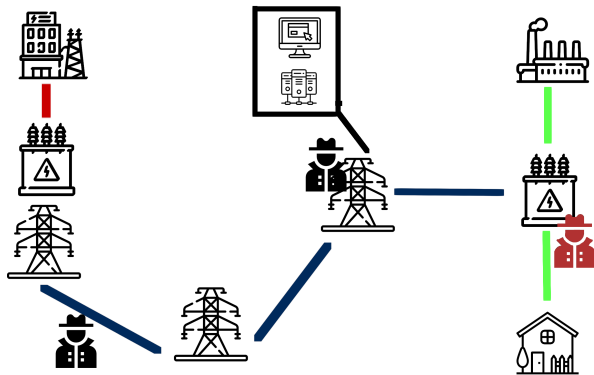
- ▶ lack of (good) training data
- ▶ **state estimation** (SE):  
assumption communicated data is correct
- ▶ multiple security solutions are needed

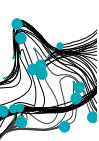


# Attack model



# Attack model





# Attack model

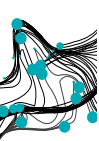
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- ▶ able to get into SCADA communication
- ▶ eavesdrop, intercept, manipulate and exchange messages
- ▶ knowledge about protocols and common grid architecture







# Approach

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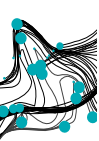
## ► process-awareness<sup>1</sup>



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<sup>1</sup> J. J. Chromik, A. Remke, and B. Haverkort, "An integrated testbed for locally monitoring SCADA systems in smart grids," Energy Informatics, vol. 1, pp. 1-29, 2018.

<sup>2</sup> V. Menzel, J. L. Hurink and A. Remke, "Securing SCADA networks for smart grids via a distributed evaluation of local sensor data," SmartGridComm, 2021, pp. 405-411.



# Approach

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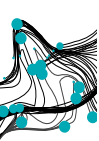
- ▶ process-awareness<sup>1</sup>
- ▶ securing the last mile



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# Approach

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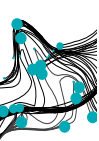
- ▶ **process-awareness**<sup>1</sup>
- ▶ securing the last mile
- ▶ fixed set of rules to decide:  
does this data/command make sense?



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# Approach

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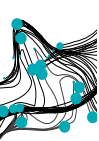
- ▶ process-awareness<sup>1</sup>
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- ▶ local evaluation: attacks within a field station



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# Approach

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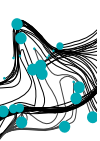


- ▶ process-awareness<sup>1</sup>
- ▶ securing the last mile
- ▶ fixed set of rules to decide:  
does this data/command make sense?
- ▶ local evaluation: attacks within a field station
- ▶ neighbourhood evaluation<sup>2</sup>: attacks against a complete  
field station

---

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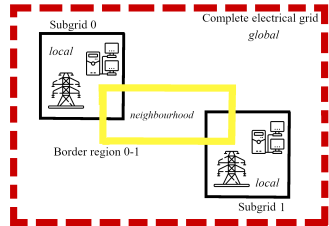
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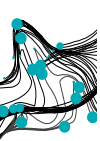


# Approach



- ▶ two field stations supervising each other

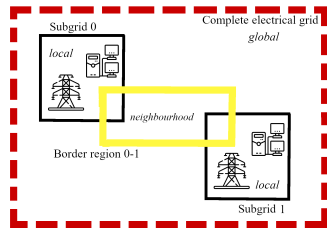


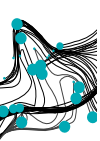


# Approach



- ▶ two field stations supervising each other
- ▶ check done with every neighbour

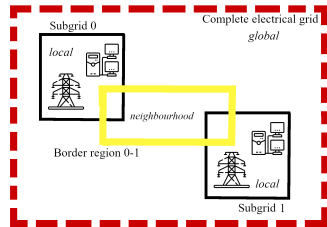




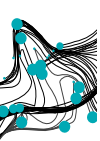
# Approach



- ▶ two field stations supervising each other
- ▶ check done with every neighbour
- ▶ additional communication channels



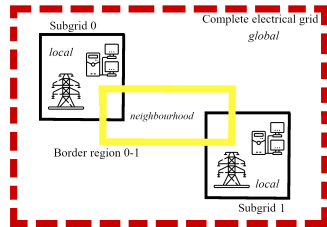


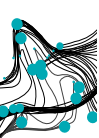


# Approach



- ▶ two field stations supervising each other
- ▶ check done with every neighbour
- ▶ additional communication channels
- ▶ OPC-UA



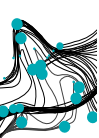


# Approach

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- ▶ formal model for splitting the grid & set of requirements



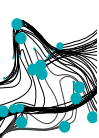


# Approach

---

- ▶ formal model for splitting the grid & set of requirements
- ▶ testbed with the co-simulation framework MOSAIK featuring two subgrids and one border region



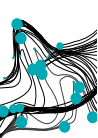


# Approach

---

- ▶ formal model for splitting the grid & set of requirements
- ▶ testbed with the co-simulation framework MOSAIK featuring two subgrids and one border region
- ▶ attack tool for eavesdropping, replay attacks and manipulations



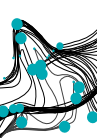


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- ▶ formal model for splitting the grid & set of requirements
- ▶ testbed with the co-simulation framework MOSAIK featuring two subgrids and one border region
- ▶ attack tool for eavesdropping, replay attacks and manipulations
- ▶ prototype implementation of an IDS detectable:





# Approach

---



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- ▶ prototype implementation of an IDS detectable:
  - ▶ attack within a subgrid





# Approach

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- ▶ formal model for splitting the grid & set of requirements
- ▶ testbed with the co-simulation framework MOSAIK featuring two subgrids and one border region
- ▶ attack tool for eavesdropping, replay attacks and manipulations
- ▶ prototype implementation of an IDS detectable:
  - ▶ attack within a subgrid
  - ▶ attack within a border region

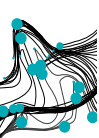


# Approach

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- ▶ formal model for splitting the grid & set of requirements
- ▶ testbed with the co-simulation framework MOSAIK featuring two subgrids and one border region
- ▶ attack tool for eavesdropping, replay attacks and manipulations
- ▶ prototype implementation of an IDS detectable:
  - ▶ attack within a subgrid
  - ▶ attack within a border region
  - ▶ attack within a subgrid, without causing local alerts





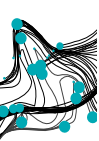
# Truly distributed approach I

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- ▶ before: **docker** is great!





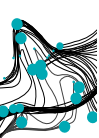
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- ▶ before: **docker** is great!
- ▶ but still one piece of hardware ...





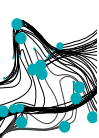
# Truly distributed approach I

---



- ▶ before: **docker** is great!
- ▶ but still one piece of hardware ...
- ▶ now: testbed, monitors and control and command server each on their own **Raspberry Pi**





## Side note I: docker

---



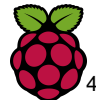
- ▶ OS-level virtualization to deliver software in **containers**
- ▶ free (and premium) platform as a service
- ▶ makes it easy to start multiple **containers** in light-weight environments, functioning every time



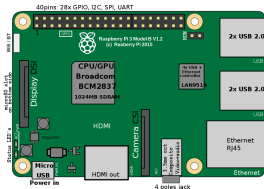
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<sup>3</sup>[https://en.wikipedia.org/wiki/Docker\\_\(software\)#/media/File:Docke\\_r\\_logo.svg](https://en.wikipedia.org/wiki/Docker_(software)#/media/File:Docke_r_logo.svg)

## Side note II: Raspberry Pi



- ▶ popular single-board computer for education and DIY projects
- ▶ modular system to equip with all different sorts of additions
- ▶ here: Raspberry Pi 3 Model B V1.2



5

<sup>4</sup> [https://en.wikipedia.org/wiki/File:Raspberry\\_Pi\\_Logo.svg](https://en.wikipedia.org/wiki/File:Raspberry_Pi_Logo.svg)

<sup>5</sup> <https://en.wikipedia.org/wiki/File:RaspberryPi3B.svg>



## Truly distributed approach II

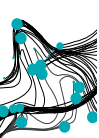
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Adaptions:

- ▶ need to configure **wheels** for ARM architecture





## Truly distributed approach II

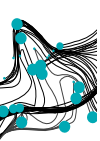
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### Adaptions:

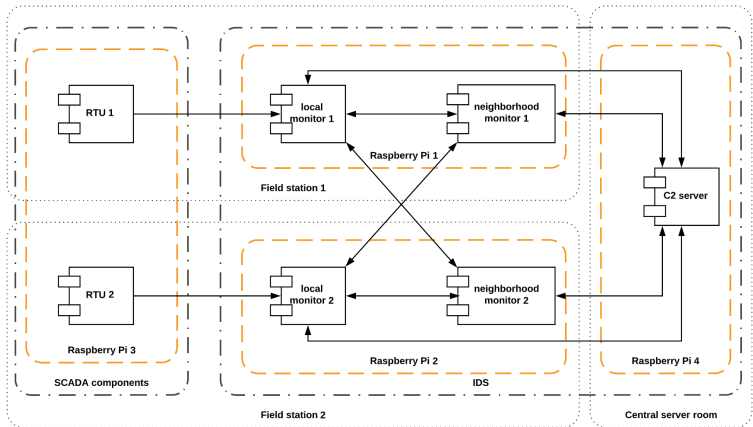
- ▶ need to configure **wheels** for ARM architecture
- ▶ need to make IP addresses and ports externally available from outside the containers



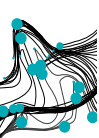


# Truly distributed approach II

Adaptions:







## Truly distributed approach II

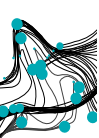
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### Results:

- ▶ in replay mode: same alerts are triggered as in centralized execution  
(... after bug fix)





## Truly distributed approach II

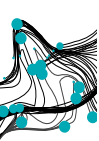
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### Results:

- ▶ in replay mode: same alerts are triggered as in centralized execution  
(... after bug fix)
- ▶ all Raspberry Pis are bored





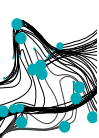
## Truly distributed approach II



```
...monitor1: ~ -- ssh pi@monitor1 ...  ...onitor1: ~ -- ssh pi@monitor1 ...  ...itor1: ~ -- ssh pi@monitor1 +
top - 23:36:52 up 2:02, 5 users, load average: 1.28, 1.40, 1.11
Tasks: 184 total, 2 running, 182 sleeping, 0 stopped, 0 zombie
%Cpu(s): 6.2 us, 0.9 sy, 0.0 ni, 92.5 id, 0.2 wa, 0.0 hi, 0.2 si, 0.0 st
MiB Mem : 722.1 total, 83.1 free, 356.3 used, 482.8 buff/cache
MiB Swap: 100.0 total, 97.7 free, 2.2 used. 504.0 avail Mem
```

No value smaller than 85% idle was observed.





## Truly distributed approach II

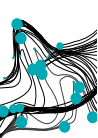
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### Results:

- ▶ in replay mode: same alerts are triggered as in centralized execution  
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- ▶ increased speed of new measurement is no problem





## Truly distributed approach II

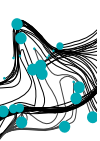
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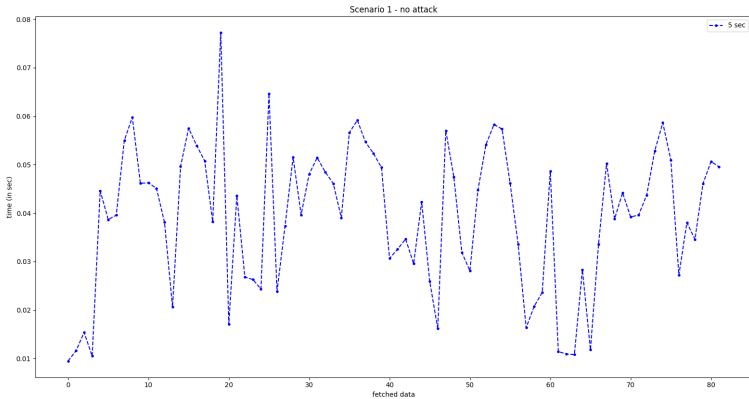
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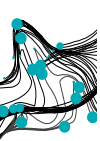
- ▶ in replay mode: same alerts are triggered as in centralized execution  
(... after bug fix)
- ▶ all Raspberry Pis are bored
- ▶ increased speed of new measurement is no problem
- ▶ evaluation is quick



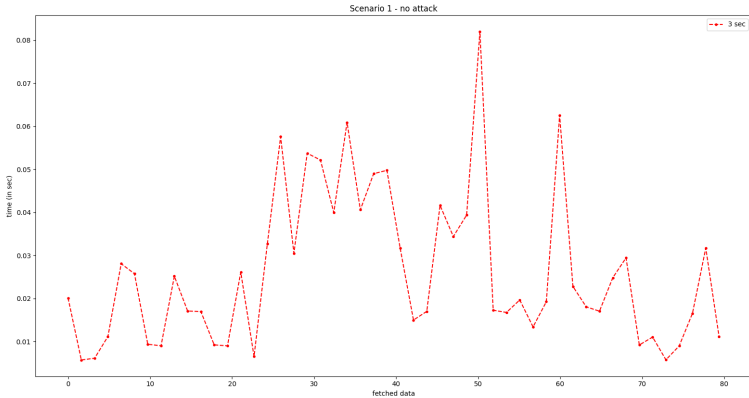


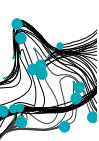
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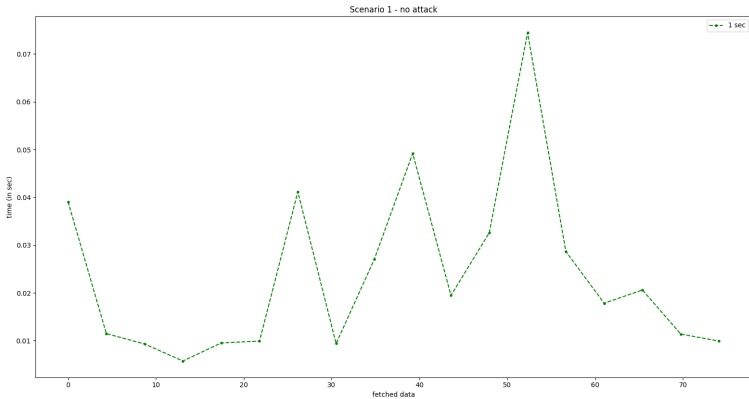


# Truly distributed approach II





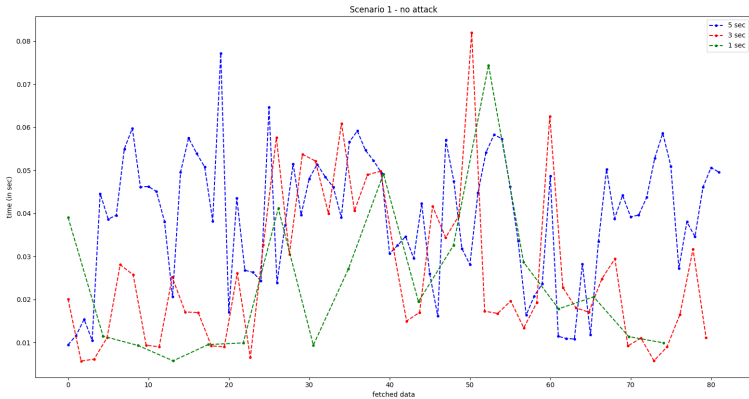
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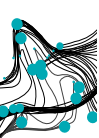






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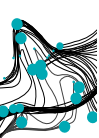
# Properties for real-life test case

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- ▶ Confidentiality
- ▶ Integrity
- ▶ Availability



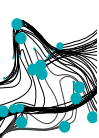


# Properties for real-life test case

---

- ▶ central command and control sever:  
*traditional* data center protection





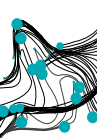
# Properties for real-life test case

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- ▶ central command and control sever:  
*traditional* data center protection
- ▶ monitors:





# Properties for real-life test case

---

- ▶ central command and control sever:  
*traditional* data center protection
- ▶ monitors:
  - ▶ Raspberry Pis were too strong/strong enough





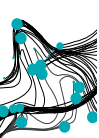
# Properties for real-life test case

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- ▶ central command and control sever:  
*traditional* data center protection
- ▶ monitors:
  - ▶ Raspberry Pis were too strong/strong enough
  - ▶ lacking TPM & real-time clock





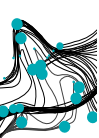
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  - ▶ hard to protect against DDOS





# Properties for real-life test case

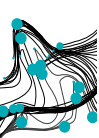
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*traditional* data center protection
- ▶ monitors:
  - ▶ Raspberry Pis were too strong/strong enough
  - ▶ lacking TPM & real-time clock
  - ▶ hard to protect against DDOS
  - ▶ BUT we can detect it quickly :-)







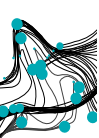
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  - ▶ lacking TPM & real-time clock
  - ▶ hard to protect against DDOS
  - ▶ BUT we can detect it quickly :-)
- ▶ in general: **OPC-UA** is a good choice (for C, I and A)





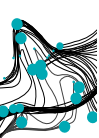
# Properties for real-life test case

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- ▶ central command and control sever:  
*traditional* data center protection
- ▶ monitors:
  - ▶ Raspberry Pis were too strong/strong enough
  - ▶ lacking TPM & real-time clock
  - ▶ hard to protect against DDOS
  - ▶ BUT we can detect it quickly :-)
- ▶ in general: **OPC-UA** is a good choice (for C, I and A)
- ▶ VPN could be an addition





## Next steps

---



- ▶ real-world data
- ▶ thresholds
- ▶ more scenarios, more Raspberry Pis
- ▶ other HW
- ▶ experimenting with different monitor positions
- ▶ questions?

