

Challenge-Based Learning in MSc Robotics

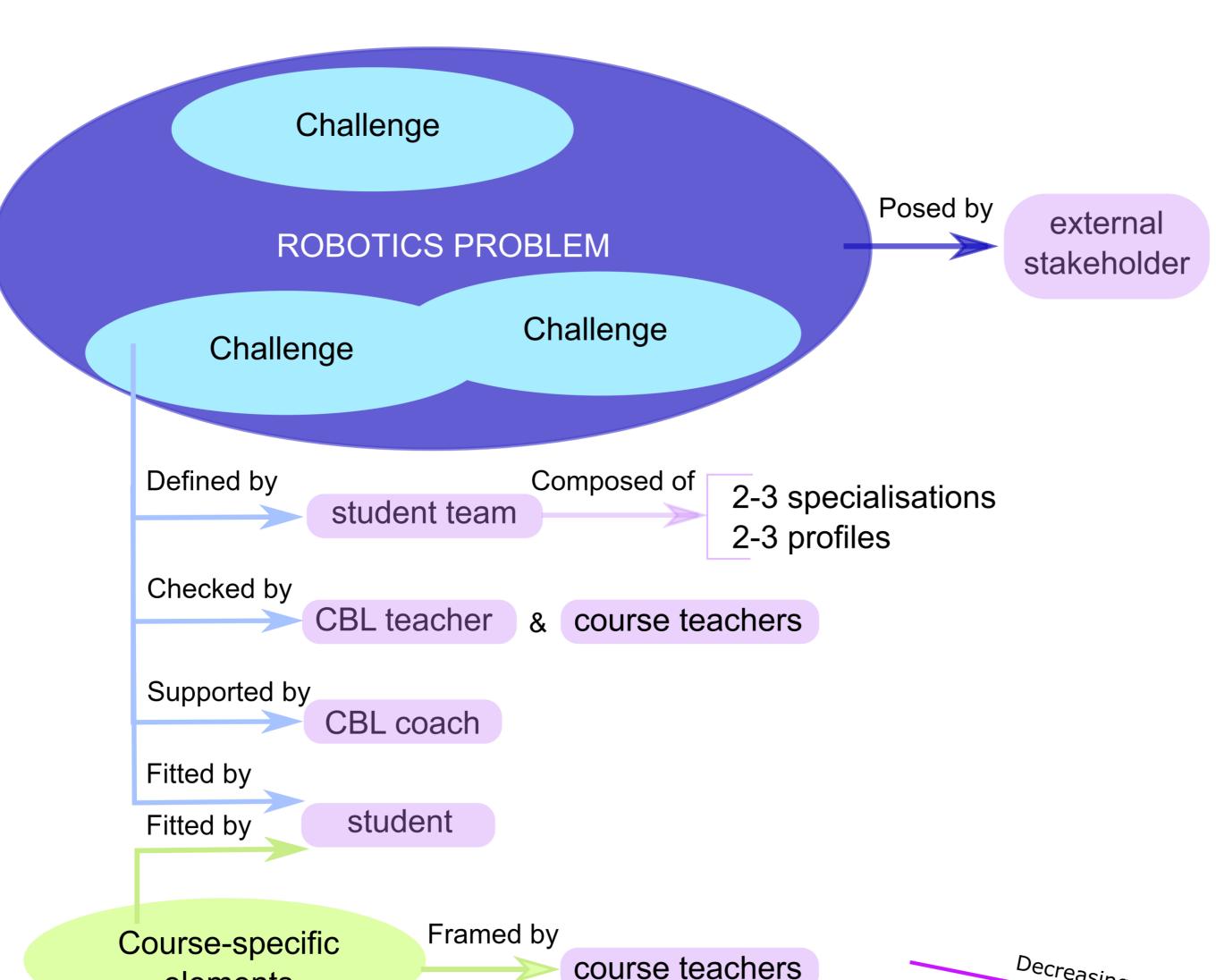
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MSc-Robotics Programme

- 3 Specialisations (6 courses, 30 EC)
 - Mechatronics & Physical Al
 - Algorithms & Software Al
 - Human-Robot Interaction & Social Al
- 3 Profiles (2 electives, 10 EC)
 - Research
 - Design
 - Innovation & Entrepreneurship
- 4 electives (20 EC)
- Internship / Academic-Skills project / Electives
- MSc-Thesis Project

CBL in MSc-Robotics Programme

- Challenging, open-ended problems from practice
- Better preparation for MSc-Thesis project
- Better preparation for professional career
- Better preparation for continuous learning
- One project per quartile
- Multidisciplinary student teams
- Growing complexity of projects
- CBL teachers & course teachers



Coordination / teaching

- CBL teachers
 - next to course teachers
- CBL coaches (TAs)
- Educational support

Student-Team Composition

- Teams span multiple specialisations
- Teams span multiple profiles for multidisciplinarity

One Project per Quartile

- Each quartile one CBL project
- Feedback / assessment per project
- Reset each quarter eases process

Maturity of CBL projects

Complexity grows

elements

- stakeholder involvement
- course topics
- Decrease support
 - more freedom
- Focus from learning to performing

	Decreasing support					Increasing complexity						
	Q1			Q2			Q3			Q4		
Y1												
Y2 —	Intro CE	3L	CBL2,	1-3 co	urses	CBL3	, 1-3 cc	ourses	CBL4	, 1-3 cc	ourses	
СВ	L in intern	•	ctives			CBL in	n MSc-t	hesis p	roject			
aCo	ademic pro	jeci/ele	cuves							·	ortfolio portfolio	

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