UNIVERSITY | THERMAL OF TWENTE. | ENGINEERING

Application of POD and DMD in Fluid Dynamics Analysis

Alireza Ghasemi

MAGISTER



See more at https://www.magister-itn.eu/

This project has received funding from the European Union's Horizon 2020 research and innovation programme under the Marie Sklodowska-Curie Grant Agreement No 766264.

OUTLINE

- Introduction to POD
- Simple Demo
- Practical Example
- Short Q&A
- Introduction to DMD
- Practical Example
- ► Q&A

ALGORITHM CLASSIFICATION



ALGORITHM CLASSIFICATION



POD: PROPER ORTHOGONAL DECOMPOSITION

- Also known as PCA: Principal Component Analysis
- Original formulation in 1967 by J. Lumley
- Widely used in Fluid Dynamics
- Many variations exist:
 - Missing data
 - Noisy or corrupted data
 - Multiple datasets
 - Multiscale

$$y(x,t) = \sum_{j=1}^m u_j(x) a_j(t)$$

- Decomposing time variant systems into spatial and temporal parts
- In general, not a unique decomposition
- POD finds this decomposition with smallest "m"

$$Y = \begin{bmatrix} u(x_1, t_1) & u(x_1, t_2) & \dots & u(x_1, t_m) \\ u(x_2, t_1) & u(x_2, t_2) & \dots & u(x_2, t_m) \\ \vdots & \vdots & \ddots & \vdots \\ u(x_n, t_1) & u(x_n, t_2) & \dots & u(x_n, t_m) \end{bmatrix}$$

- Spatial dimension: n
- Temporal dimension: m
- Various assembly techniques are available



 \blacktriangleright We can trim U and Σ while keeping the same results

- \blacktriangleright U and V are unitary. Σ is diagonal with decreasing positive entries
- ▶ We can further trim for an approximation to Y



- \blacktriangleright We can trim U and Σ while keeping the same results
- \blacktriangleright U and V are unitary. Σ is diagonal with decreasing positive entries
- ▶ We can further trim for an approximation to Y



- \blacktriangleright We can trim U and Σ while keeping the same results
- \blacktriangleright U and V are unitary. Σ is diagonal with decreasing positive entries
- ▶ We can further trim for an approximation to Y



- \blacktriangleright We can trim U and Σ while keeping the same results
- \blacktriangleright U and V are unitary. Σ is diagonal with decreasing positive entries
- ▶ We can further trim for an approximation to Y

POD: MODES AND COEFFICIENTS

$$Y = U \Sigma V^* \approx U_r \Sigma_r V_r^*$$

Optimality of POD: Rank-r approximation minimizes the Frobenius norm

$$\|Y-Y_r\|_F = \sqrt{\sum_{j=1}^n \sum_{k=1}^m (Y-Y_r)_{jk}^2}$$

- U contains the POD modes
- \blacktriangleright Σ contains POD singular values
- ► V contains the right singular vector or POD coefficients

DEMO

Let's try it with the following synthetic signal

$$\begin{split} s_1 &= a_1 \exp\left(-\frac{(x-b_1)^2}{2c_1^2}\right) \\ s_2 &= a_2 \exp\left(-\frac{(x-b_2)^2}{2c_2^2}\right) \end{split}$$

$$y(x,t) = s_1 \sin(2\pi\omega_1 t) + s_2 \sin(2\pi\omega_2 t)$$

EXAMPLE: LES OF UT BURNER



- Identify mean values
- Breakdown into modes
- Extract flow structures
- ► Able to identify PVC
- Energy breakdown of modes



- Identify mean values
- Breakdown into modes
- Extract flow structures
- ► Able to identify PVC
- Energy breakdown of modes



- Identify mean values
- Breakdown into modes
- Extract flow structures
- ► Able to identify PVC
- Energy breakdown of modes



- Identify mean values
- Breakdown into modes
- Extract flow structures
- ► Able to identify PVC
- Energy breakdown of modes



DMD: DYNAMIC MODE DECOMPOSITIONS

- ► Think of it as POD + DTFT
- Developed in 2010 by P. Schmid
- DMD modes are not orthogonal like POD
- Many extensions exist:
 - ► GPU CUDA implementation
 - Compressed sensing
 - Noisy data
 - Multiresolution
 - Robustness

KOOPMAN ANALYSIS BASICS

- Formalism for dynamic systems: Koopman Theory 1931
- Imagine the following discrete time system with state vector x

$$x_{n+1} = F(x_n)$$

Observables of the state vector or functions of x is defined as g(x)
Koopman operator evolves the system in the following manner

$$g(x_{n+1}) = Kg(x_n)$$

 Koopman operator turns a finite nonlinear dynamical system in vector space into an infinite dimensional linear system in function space g(x)
MAGISTER ITN UNIVERSITY OF TWENTE.

DMD: MAIN IDEA

- DMD gets us the best linear approximation to a dynamical system by approximating the infinite-dimensional Koopman operator
- Let's assemble our Y matrix in the two following forms

$$\mathbf{Y} = \begin{bmatrix} | & | & & | \\ y_1 & y_2 & \dots & y_{m-1} \\ | & | & & | \end{bmatrix} \qquad \mathbf{Y}' = \begin{bmatrix} | & | & & | \\ y_2 & y_3 & \dots & y_m \\ | & | & & | \end{bmatrix}$$

Looking for an optimally locally linear approximation in the following form

$$Y' \approx AY$$

DMD: ALGORITHM

- Best-fit A matrix is given by $A = Y'Y^{\dagger}$
- This, again, minimizes the aforementioned Frobenius norm
- **>** By using SVD or $Y = U\Sigma V^*$ we can work out the following

 $A = Y' V \Sigma^{-1} U^*$

For efficiency, instead of A, we compute \tilde{A} which is the projection of A onto POD modes in the following manner

 $\tilde{A} = U^*AU = U^*Y'V\Sigma^{-1}$

DMD: ALGORITHM

- ► Now we compute the eigen decomposition of \tilde{A} or simply: $\tilde{A}W = W\Lambda$
- \blacktriangleright Eigenvalues of \tilde{A} are the same as A
- lt can be shown that eigenvectors of $\Phi = UW$ are the same as A

 $\Phi = Y' V \Sigma^{-1} W$

- We compute eigenvectors (modes) and eigenvalues (time dynamics) of A without ever actually computing A
- ▶ We can still adopt a low rank approach like before

DMD: CODE

- 1. Prepare the data matrix Y and Y' in the correct form
- 2. Run economy SVD
- 3. Find \tilde{A}
- 4. Find *W* and *D*
- 5. Find time eigenvalues
- 6. Find DMD modes
- 7. Find DMD mode coefficients
- 8. Construct your approximation

```
[U ,S, V]=svd(Y, 'econ');
```

```
Atilde = U' *Yp*V/S;
```

```
[W, D] = eig(Atilde);
```

```
omega = log(diag(D))/dt;
```

```
Phi = Yp*V/S*W;
```

```
b = Phi \setminus Y(:, 1);
```

Ydmd = Phi*(b.exp(omega*time));

EXAMPLE: LES OF UT BURNER



MAGISTER ITN UNIVERSITY OF TWENTE.

25



Thank you for your attention! Stay healthy :)